

MagTek Universal SDK

**For MMS Devices
Test Console Manual (Linux)**

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Table 0.1 – Revisions

Rev Number	Date	Notes
100	February 1, 2024	Initial release.

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1 Introduction

This document provides instructions to use the MTUSDKNET Test Console. This test EMV transactions, sends configuration files and updates firmware.

It is part of a larger library of documents designed to assist Secure Card Readers implementers, which includes the following documents available from MagTek:

- ***D998200570 MAGTEK UNIVERSAL SDK PROGRAMMER'S MANUAL (LINUX)***
- ***D998200489 DYNAPROX PROGRAMMER'S MANUAL (COMMANDS)***
- ***D998200383 DYNAFLEX PRODUCTS PROGRAMMER'S MANUAL (COMMANDS)***

2 How to Connect to MTUSDK Test Console

To connect via an interface follow these steps:

2.1 Connect via USB Interface

- 1) Connect the device to the USB port of the Linux computer.
- 2) The first time, allow a moment for the host to recognize the device.
- 3) The console automatically connects to the first USB DynaProx it finds.

2 - How to Connect to MTUSDK Test Console

2.2 Connect via Serial Interface

- 1) Connect the device to the Serial port of the Linux computer.
- 2) Edit `main.cpp` file.
- 3) Below the `reopen:` label, set the proper Serial connection type by uncommenting the `"dev = CoreAPI"` that matches the port to be used.

```
reopen:

    auto devices = CoreAPI::getDeviceList();
    IDevice* dev = NULL;

    // USB device detected ?
    if (devices.size() > 0)
    {
        // open first USB device
        dev = devices.at(0);
        //

    }
    else
    {
        //dev = CoreAPI::getDevice(MTU_DEVICE_TYPE::SCRA,
MTU_DEVICE_CONNECTION_TYPE::MTU_SERIAL, "port=/dev/ttyS1");

        // open a DynaProx from ttyS1
        //dev = CoreAPI::getDevice(MTU_DEVICE_TYPE::MMS,
MTU_DEVICE_CONNECTION_TYPE::MTU_SERIAL, "port=/dev/ttyS1");

#ifdef TEST_MMS
        // open a DynaProx from serial0
        dev = CoreAPI::getDevice(MTU_DEVICE_TYPE::MMS,
MTU_DEVICE_CONNECTION_TYPE::MTU_SERIAL, "port=/dev/serial0");
#else
        // open a mDynamo from serial0
        dev = CoreAPI::getDevice(MTU_DEVICE_TYPE::SCRA,
MTU_DEVICE_CONNECTION_TYPE::MTU_SERIAL, "port=/dev/serial0");
#endif

        // open a mDynamo from USB to RS232 port (first one)
        //dev = CoreAPI::getDevice(MTU_DEVICE_TYPE::SCRA,
MTU_DEVICE_CONNECTION_TYPE::MTU_SERIAL, "port=/dev/ttyUSB0");
    }
```

- 4) After editing `main.cpp`, rebuild the console with `make -f makefile.mms`.
The output file is `mtusdk_test.mms`.

3 - How to use the MTUSDK Test Console

3 How to use the MTUSDK Test Console

The following instructions are for using the MTUSDK Test console on a Linux operating system. In these examples, lines are removed and replaced with “...” for readability.

3.1 EMV Transaction

- 1) To perform an EMV transaction, select operation 1 or 2.

```
SDK version 118
  Model:
    Name: port=/dev/serial0
  <- (Connection State) connected
  <- (Operation Status) operation_done,0000D101,Operation Done,00000000
  <- (Device Response) AA...
    Serial Number: B62CA5F0
Select an operation :
1. Transaction (Quick Chip)
2. Transaction (Full)
3. Send TERMINAL configuration file (00000000)
4. Update firmware
5. Send PROCESSING configuration file (00000100)
6. Send ENTRYPOINT configuration file (00000200)
7. Send CA KEYES configuration file (00000300)
8. Send AMEXDRL configuration file (00000500)
0. Quit
```

- 2) The console calls startTransaction()
3) Continue the transaction by tapping a contactless card.
4) Message events are shown to tap and remove the card.

```
<- (Display Message) WELCOME
[WELCOME]
<- (Device Notification)
AA00810483001803820402010200848200141803810100820101838200085441502043
415244
<- (Display Message) TAP CARD
[TAP CARD]
<- (Device Notification)
AA008104830018038204020101008482001718038101008201018382000B52454D4F56
452043415244
<- (Display Message) REMOVE CARD
[REMOVE CARD]
<- (Device Notification) AA00810483000101820420010400
<- (Transaction Status) card_detected
<- (Device Notification)
```

3 - How to use the MTUSDK Test Console

- 5) In the event handler `OnEvent ()`, an ARQC event is fired as
`EVENT_TYPE_AuthorizationRequest`

```
<- (Request Authorization)
01E9F98201E5DFDF540AFFFF9876543210200015DFDF550182DFDF2507423632434135
46FA8201C3708201BDFDF530100DFDF4D273B35343433303030303430303033343535
3D3030. . .
```

- 6) If the selected operation was #2 Transaction (Full), the console sends the ARPC to the device by
calling `sendAuthorization ()`.

```
SendAuthorization - FF7413DFDF250742353143364543FA0670048A023030
```

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3.2 Send Configuration Files

- 1) To send a configuration files, select operation 3, 4, 5, 6, 7, or 8. Each option sends a separate file.

Select an operation :

1. Transaction (Quick Chip)
2. Transaction (Full)
3. Send TERMINAL configuration file (00000000)
4. Update firmware
5. Send PROCESSING configuration file (00000100)
6. Send ENTRYPOINT configuration file (00000200)
7. Send CA KEYES configuration file (00000300)
8. Send AMEXDRL configuration file (00000500)
0. Quit

- 2) The console calls `sendFile()` to send `cfg00000000.bin` (Terminal configuration).

From this point, the SDK sends the file in packets to the device. After each packet is received by the device, the SDK is notified and triggers the callback `OnProgress()`. The console displays the progress event.

```
<- (Operation Status) operation_done,0000D812,Operation Done,00000000
<- (Device Response) AA0081048203D812820400000000
progress (33)
. . .
progress (100)
result (0)
```

- 3) The console shows the end result of each upload as `result (0)`. The result is handled within SDK event function `OnResult()`. 0 = success.

```
<- (Operation Status) operation_done,0000D812,Operation Done,00000000
<- (Device Response) AA0081048203D812820400000000
progress (33)
. . .
progress (100)
result (0)
sendfile(0000000000, filedata) -> 0
```

3 - How to use the MTUSDK Test Console

3.3 Update Firmware

- 1) To update the firmware on the device, select operation 4.

```
Select an operation :
1. Transaction (Quick Chip)
2. Transaction (Full)
3. Send TERMINAL configuration file (00000000)
4. Update firmware
5. Send PROCESSING configuration file (00000100)
6. Send ENTRYPOINT configuration file (00000200)
7. Send CA KEYES configuration file (00000300)
8. Send AMEXDRL configuration file (00000500)
0. Quit
```

- 2) The console calls `updateFirmware()`.

From this point, the SDK sends the firmware in packets to the device. After each packet is received by the device, the SDK is notified and triggers the callback `OnProgress()`. The console displays each progress event.

```
progress (1)
. . .
progress (68)
progress (99)
progress (100)
```

- 3) DO NOT POWER CYCLE OR DETACH FROM HOST during this time.

- 4) When the update is complete, the console displays as shown below. 0 is success.

```
progress (100)
result(0)
updateFirmware(1, filedata) -> 0
```

3 - How to use the MTUSDK Test Console

3.4 Quit

1) To quit the MTUSDK Test console app, select operation “0”.

```
Select an operation :  
1. Transaction (Quick Chip)  
2. Transaction (Full)  
3. Send TERMINAL configuration file (00000000)  
4. Update firmware  
5. Send PROCESSING configuration file (00000100)  
6. Send ENTRYPOINT configuration file (00000200)  
7. Send CA KEYES configuration file (00000300)  
8. Send AMEXDRL configuration file (00000500)  
0. Quit
```